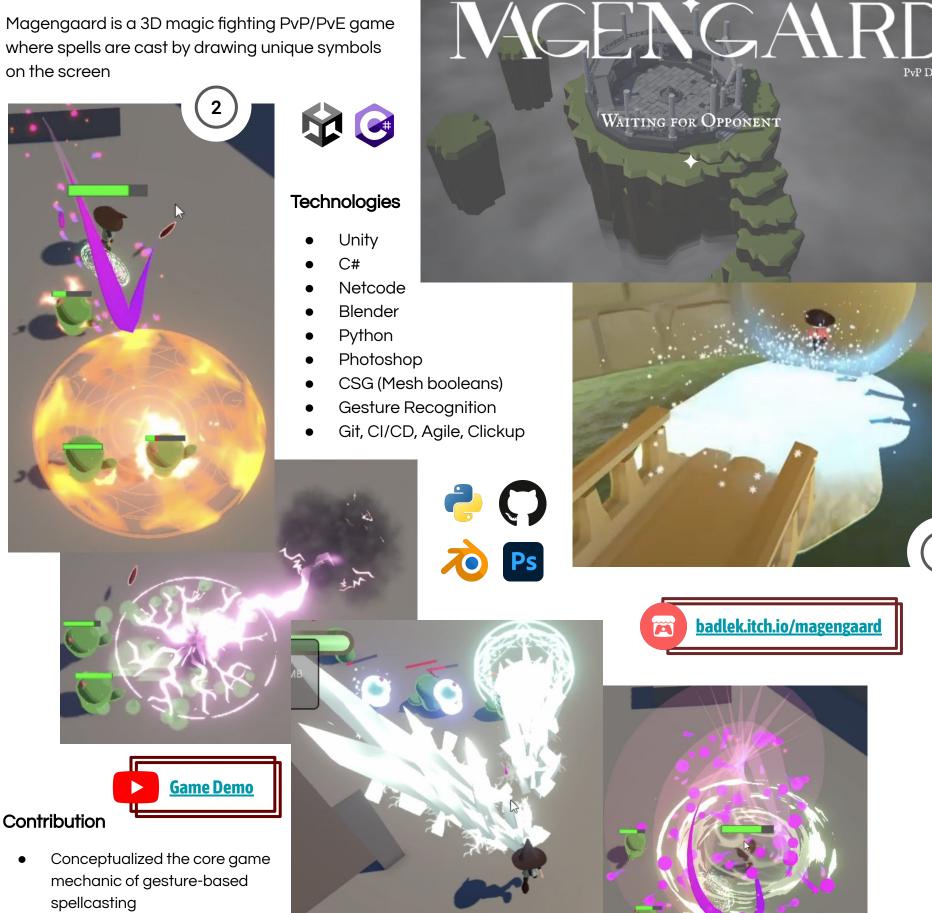


### **About**

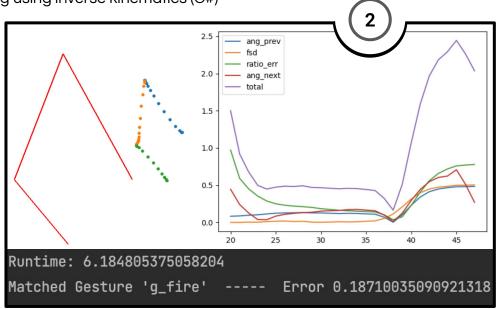
Magengaard is a 3D magic fighting PvP/PvE game where spells are cast by drawing unique symbols



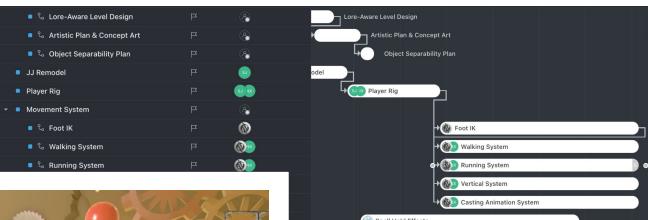
- [1] A custom in-house mesh union algorithm for freezing water (C#)
- [2] A custom in-house gesture recognition algorithm using function minimization techniques (C#)
- 3D spellbook UI with pages that turn by mouse dragging using inverse kinematics (C#) 0
- System to pick up arbitrary items off the ground (C#) 0

250+ commits including...

- Netcode for multiplayer "Demifox" bossfight where one player controls the boss! (C#)
- 3D modelling of entire second "Ruins" level in Blender
- Managed our team of 10 artists, programmers, and sound designers, implementing Agile through ClickUp
- Handled team admin tasks, coordinating share distribution and setting development timelines to prepare for upcoming Kickstarter launch and Steam release



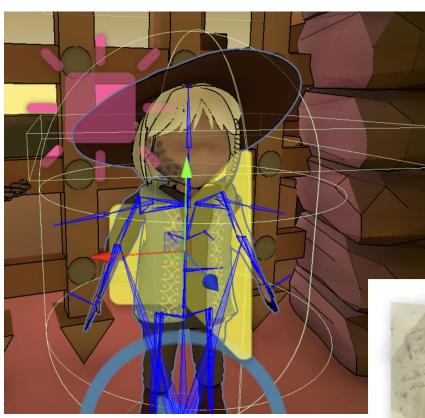
Agile project management using Clickup





Designed and modelled puzzle in second "Ruins" level

Modelled "boiler room" in second "Ruins" level

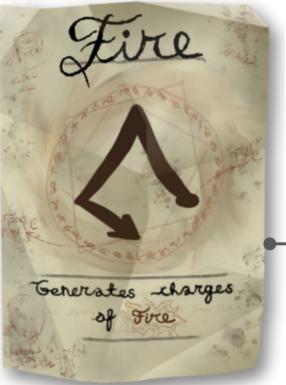


Implemented inverse kinematics and animations in code on our rigged main character

# What's Ahead

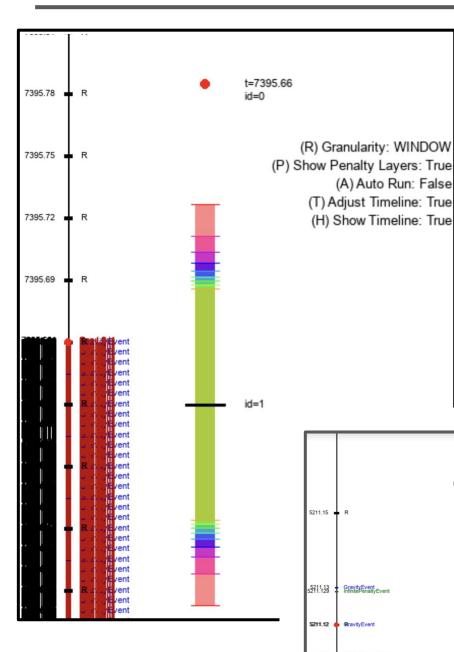
While Magengaard's current PvE experience was great for a proof of concept, we found our PvP multiplayer bossfight very fun!

We are currently working to cut scope and turn Magengaard into a well-polished competitive PvP experience, aiming for a Kickstarter launch and Steam Release in the first half of 2025



Drew the UI page assets that can be picked up throughout the game to learn new spells (A) Auto Run: False

GravityEvent InfinitePenaltyE



#### **About**

Working with supervision on replicating and innovating on an algorithm in the subfield of contact mechanics in physics simulations.

The goal is to implement this algorithm on the GPU using CUDA and leverage its high parallelizable nature

### Contribution

Read, understood, and implemented Speculative Parallel Asynchronous Contact Mechanics (SPACM) in python

Wrote an extensive visualization and logging system

leveraging tensorbaord, numpy, matplotlib, and **pygame** 

**Debugged** complex **energy behavior** issues in the simulation









# **Technologies**

- Speculative Parallel Asynchronous Contact Mechanics
- Tensorboard

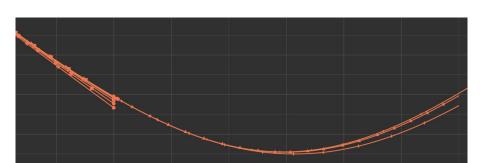
Matplotlib

- **Python**
- Pygame
- Numpy



### What's Ahead

Currently working on implementing SPACM on the GPU using **CUDA** through warp



Tensorboard particle position plot with rollback visualization

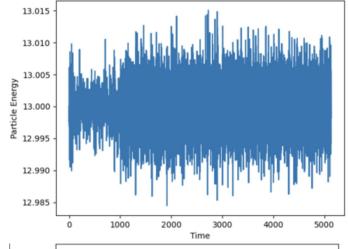


Tensorboard particle energy plot

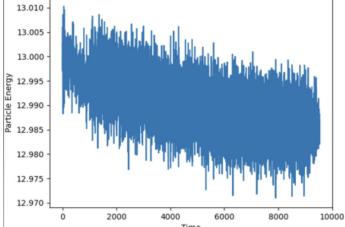
Simulation logs in binary used to debug bad energy behavior



Pygame visualizer for 1D sim: colorful layers are penalty regions which apply collision-preventing repelling forces via repeating events as shown in the timeline view on the left

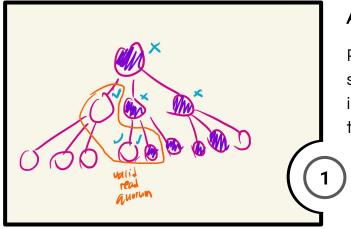


Good energy (after fix)



Bad energy behavior (before fix)

# Work



### **About**

Primary work as Research Assistant involves developing novel algorithms in the strong consistency field of distributed networks. Latest work in particular involves optimization of local reads and attempted generalization from Paxos to other classes of algorithms such as Leaderless.

Contact my supervising Professor Eyal de Lara at **delara@cs.toronto.edu** if a reference letter is needed

**procedure** read(*o*):

else

cntr := cntr + 1 and index := 0 $R := \text{closest\_read\_quorum()}$ 

wait for  $|TI| \geq \lceil \frac{n+1}{2} \rceil$ 

have been applied and return

return Read(index, o).

index := MaxP

**if** R is only the current process **then** 

/\* cntr on lines 7 and 9 is the same as line 2 \*/
send  $\langle READ, cntr \rangle$  to all processes in R

**upon receiving**  $\langle R\_ACK, cntr, T', MaxP' \rangle$ :

foreach process p in the system do

replica once all writes up to and including index

if  $(p, *) \in T'$  then  $TI := TI \cup \{p\}$ 

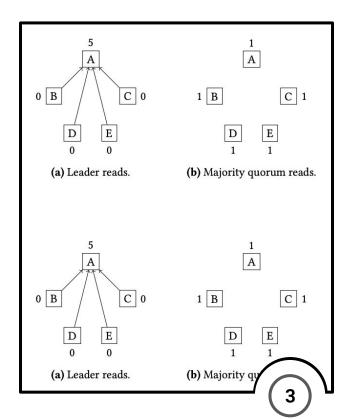
index := max(index, MaxP')

 $/\star$  Executes the read request o against the local

### Contribution

With mentorship from a PhD student...

- Contributed over **50%** of the content to a **completed research paper**.
- Worked on brainstorming and discovering over 10 minor and major innovations in the strong consistency field, particularly for local reads
- Implemented the algorithms to test them experimentally
- Formally analyzed the innovations to ensure their correctness and efficiency compared to other algorithms
- Presented my discoveries to colleagues and Professors in the lab
- Read over **50** papers in the area





### **Technologies**

Strong Consistency Algorithms (MultiPaxos, Raft, Leaderless)

10

11

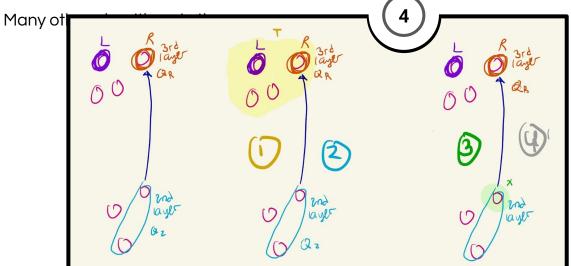
12

13

- Local Reads Algorithms (Paxos Quorum Leases , Paxos Quorum Reads)
- Clock Sync Algorithms , Lease Algorithms
- Various properties/metrics of distributed systems: Fault Tolerance ,
   Read/Write latency , Throughput , Recovery Time , etc
- Reconfiguration Algorithms: Matchmaker Paxos, Vertical Paxos,
   SMART
- Linearizability
- Quorum Intersection Algorithms: Crumbling Walls Quorums

# Captions

- 1. Tree Quorums sketch for self-verification
- 2. Small lemma from algorithm proofs
- 3. Lease diagram from local reads work
- 4. Hierarchy scenario comparisons from local reads work



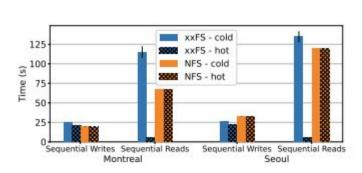


Fig. 7: FIO benchmark. Average total time to complete a FIO benchmark of sequential writes or reads at both the Montreal and Seoul edge nodes. xxFS performs better than NFS during hot runs due to local edge caching whereas NFS flushes local cache on file closes.

4) Summary: The case studies demonstrate the advantages of xxFS in hierarchical edge deployments. They highlight the benefits of the hierarchical design, on-demand replication, localized data access, and remote notifications.

#### B. FIO Benchmark

We next compare the performance of NFS and xxFS using the FIO benchmark [2]. A FIO execution is performed by creating a new directory at the root node in California, which is pre-populated with five files totaling approximately 1GB in size. Next, a trace of sequential reads or writes is executed twice back-to-back at either the Montreal or Seoul edge node. We refer to the first and second executions of the trace as cold and hot, respectively. The traces are generated using synchronous, sequential IO, a Zipf distribution of accesses, and roughly 200,000 operations are performed, totaling 1GB of IO. Furthermore, each file remains open throughout the duration of the benchmark. We record the total time to execute the benchmark across 20 runs and plot the average of the last ten along with 99% confidence intervals in Figure 7.

The results show that xxFS performs almost identically to NFS in the cold and hot runs of the sequential writes trace when ran at the Montreal edge node. Furthermore, when the same trace is ran at the Seoul edge node xxFS performs better than NFS, indicating that xxFS handles better the increase in network latency. In the sequential reads case xxFS outperforms NFS during the hot execution. This can be attributed to the fact that all file data is already replicated at the local edge node from the previous cold run. Furthermore, NFS does not see such performance improvements from the cold to hot run due to the fact that, once a NFS file handle is closed, all cached data is flushed back to the server.



### **About**

xxFS is a **distributed file system** that optimizes for **edge** applications developed in the University of Toronto Systems & **Networks Group**. The system prototype is built in **Java** on top of Cassandra using a custom FUSE implementation

### Contribution

As **Research Assistant**, conducted an experiment using a standard file system benchmark, generated a plot, and wrote the corresponding section in the paper (final result shown on the left)

In the process, discovered several bugs in the system, 3 of which were mission critical, deducing their root cause, and fixing 2 of them in code.

e.g one of the bugs involved an obscure case of a file being shown in full from the `cat` command but not when indexed sequentially via `vim`. The cause was an indexing error when file seeking.

# **Technologies**













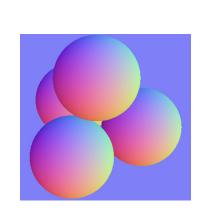
- Used Python Fabric library to automate experiment execution allowing us to perform over 100 repetitions
- **AWS** used to create an edge-like setup with over **30** machines
- FIO Benchmark Tool used to perform the standard benchmark
- Traffic Control on Ubuntu Linux used to manipulate network **tables** and simulate latencies for various experiment setups
- **Docker** used to deploy xxFS across the machines
- Deployed **NFS** across the machines to compare against xxFS

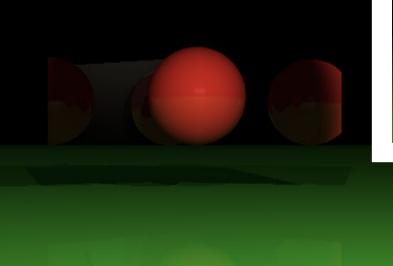
Contact my supervising Professor Eyal de Lara at delara@cs.toronto.edu if a reference letter is needed

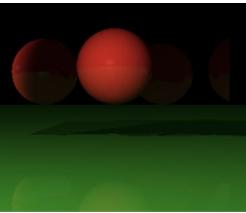
### **About**

The computer graphics course involved 8 major independent C++ projects. Here are some highlights.









# **Technologies**

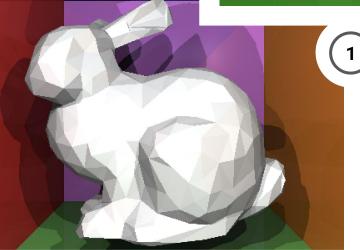
- Rigid Skinning
- C++
  - Calculus (Gradient
- **GLSL**
- descent)
- Ray Tracing
- Physics-based

animation



Linear Algebra





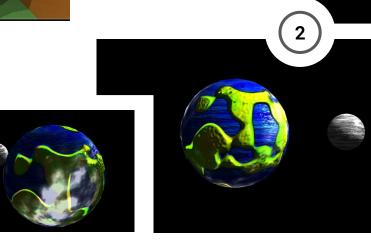
# 1: Ray Tracing

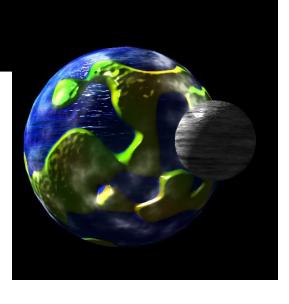
A ray tracer built in C++ capable of rendering scenes containing planes, spheres, and triangle meshes implementing shadows, reflections, and specular lighting

# 2: Shader Scene

An animated planet scene generated entirely with shader code.

Involves vertex shaders, tessellation, and fragment shaders



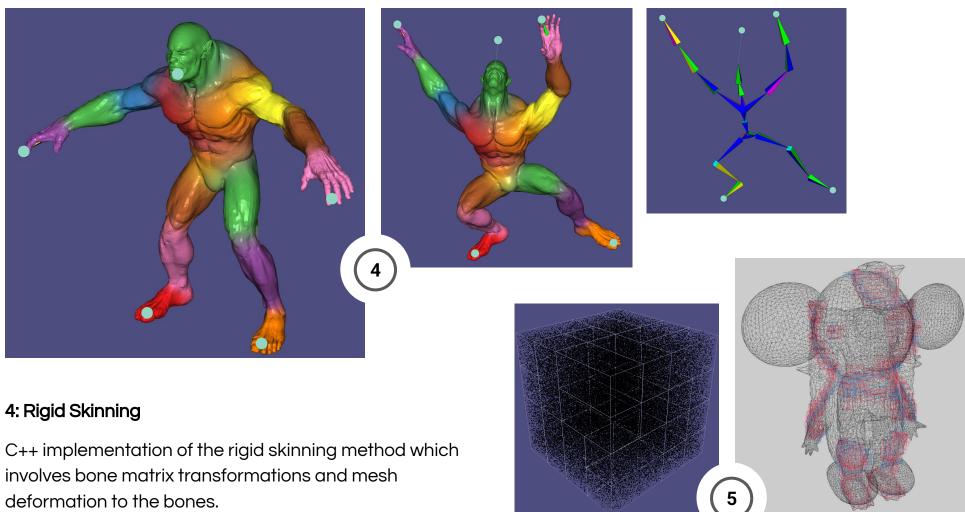


### 3: Surface Normals

Implementation of per-face normals, per-vertex normals, and per-corner normals for different shading effects



[2/2] 09/2023-12/202

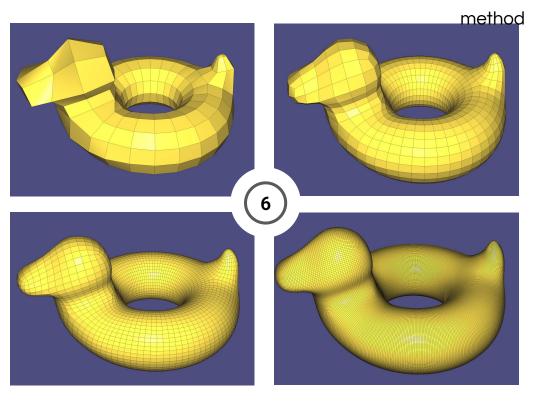


deformation to the bones.

The images show inverse kinematics achieved via gradient descent to deform the mesh via target endpoint positions.

# 5: Bounding Volume Hierarchies

Hierarchical structure to organize scene for optimizing intersection and distance queries to O(log(n)) time. Additionally implemented Devillier's triangle intersection

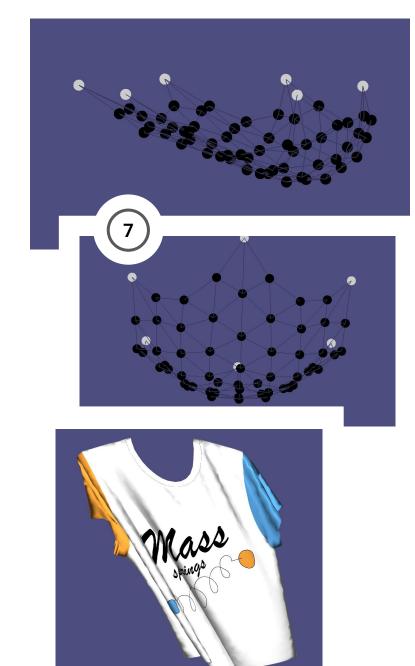


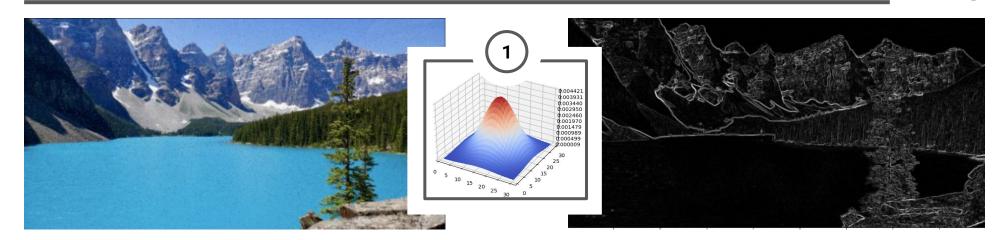
# 6: Catmull Clark Subdivision

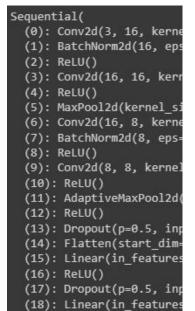
Implementation of the Catmull Clark subdivision scheme for increasing the number of polygons in a mesh

### 7: Physics-based Animation

Implemented Fast Simulation of Mass-Spring Systems paper to simulate cloth-like objects







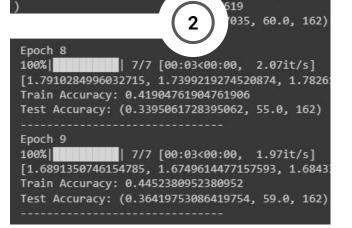
(19): Softmax(dim=1)

#### **About**

The computer vision course involved four major independent assignments. Here are some highlights.

# 1: Convolution & Edge Detection

Manually implemented convolution with numpy and used it to compute gradient magnitude of images for detecting edges

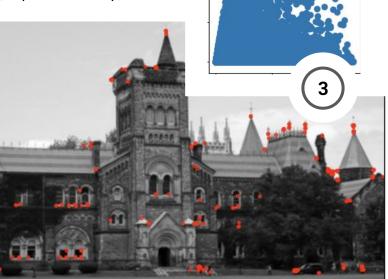






# **Technologies**

- **PyTorch**
- Conv Nets (DL)
- OpenCV / Numpy
- Computer Vision:
- SIFT, RANSAC, Homographies, Stereo (depth recovery), etc



### 3: Histogram of Gradients

Implemented an algorithm to compute the histogram of gradients for an image: a process commonly used in old-school object detection

# 2: Deep Learning

Designed and trained a conv net in Pytorch to distinguish dog breeds. Also applied transfer learning on ResNet

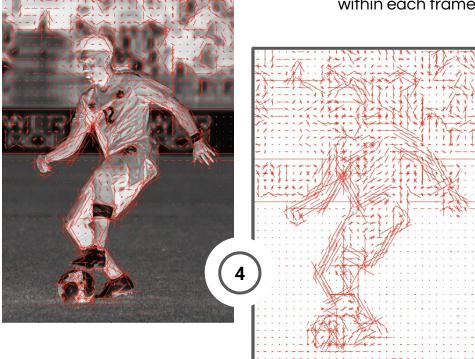
### 3: Corner Detection

Detecting corners via the eigenvalues of the second moment matrix (scatterplot for threshold-setting)

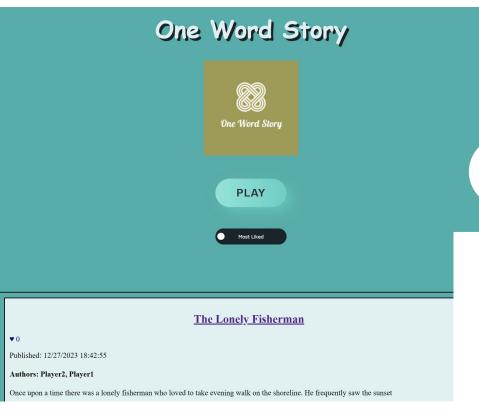
# 4: Homographies, RANSAC, SIFT

Tasked with replacing an arbitrary planar object (selected via 4 points) throughout a video, applied SIFT and RANSAC to determine a homography transformation









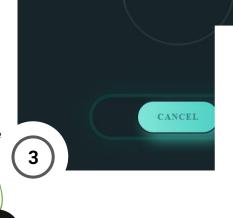
"One Word Story" is a web-based game inspired by the classic word game where players build a story one word at a time.

Developed by an eight-member team for a **Software Design** course, the platform allows players to join a match in an io-game fashion and automatically displays completed stories on its homepage after each game session.



# **Technologies**

- Java Spring Boot
- **AWS**
- PostgreSQL
- Websockets
- Multi-threading
- ReactJS
- HTML/CSS/JS
- **JQuery**
- Clean Architecture
- **SOLID Principles**
- Git / Github
- CI/CD
- Regex



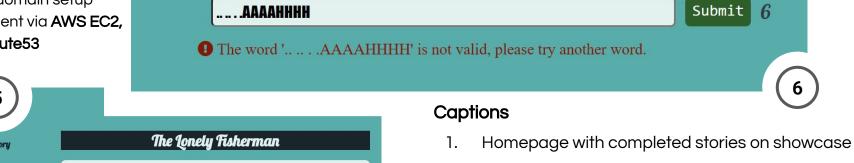
Looking for lobby...



Created the vast majority of the backend, including the

websocket code for the core game, created the frontend for the [4], [6] game page, and took care of domain setup and deployment via AWS EC2, RDS, and Route53



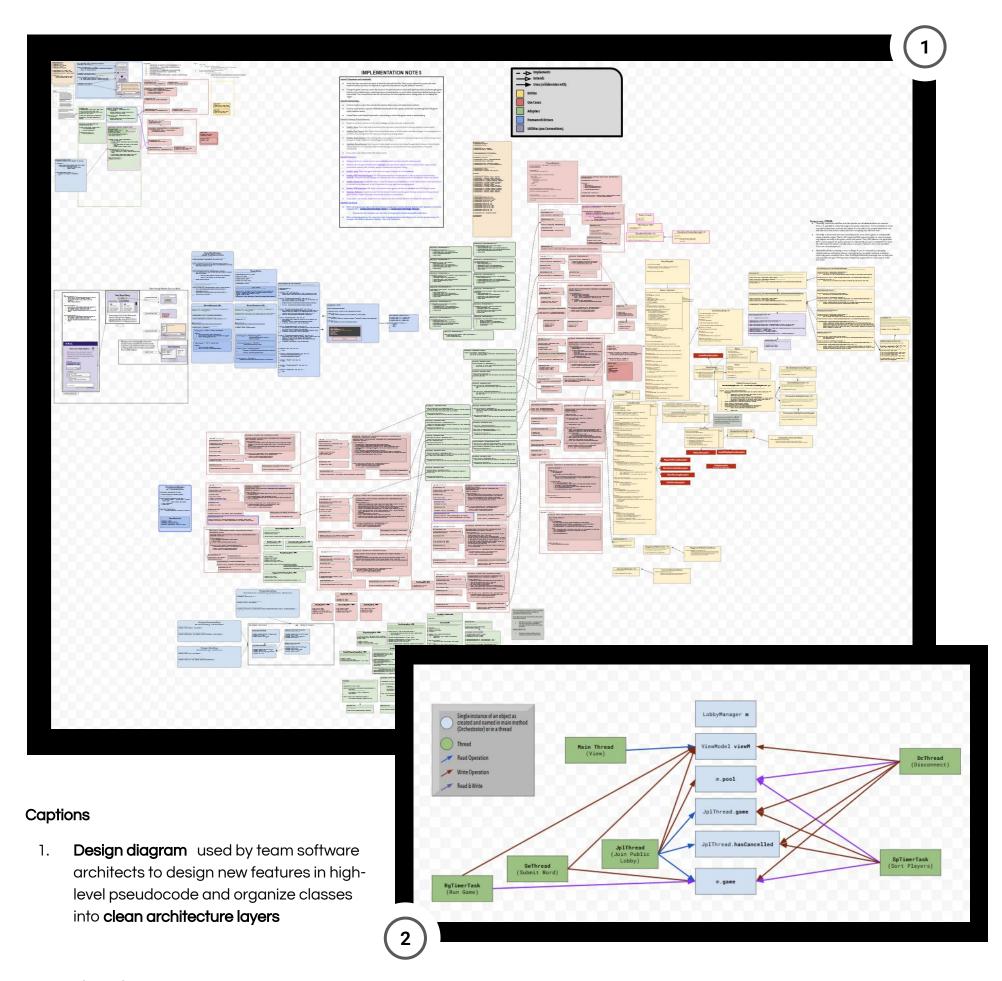




- Post-game summary shows fun statistics for each player from the finished game
- Loading screen 3.
- In-game UI 4.
- Page for a specific story, allowing comments and 5. title voting
- Regex-based input parsing

# What's Ahead

Ongoing work to port the game to ReactJS. Implementing an account system for private lobbies. Adding new game modes for variety



2. **Thread** chart mapping Use Cases threads to core objects they access for reads and writes. This was used extensively to resolve or prevent **deadlocks** 

# **Goal-Setting App**

### **About**

No matter how many goal-setting apps I tried over the years, nothing seemed to give me the exact features I needed, so finally I decided I'd write my own solution.



# **Technologies**

- Tauri
- ReactJS
- Vite
- TS/TSX/CSS
- Rust
- Postgres



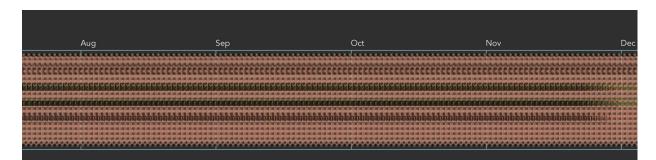




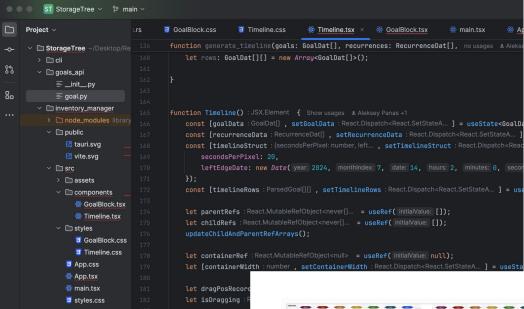












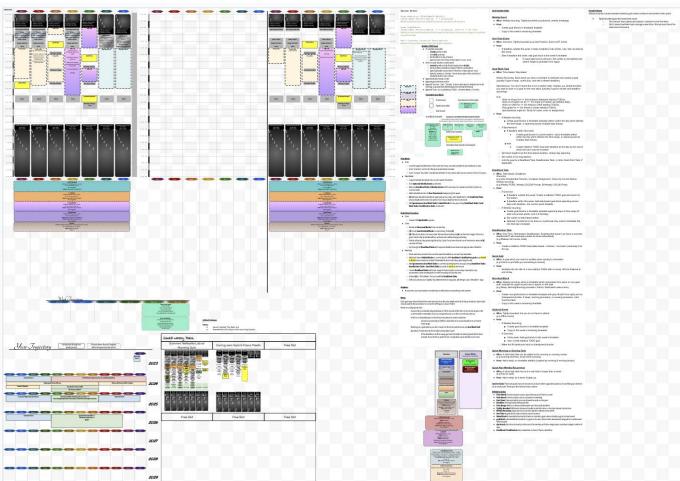
### Contribution

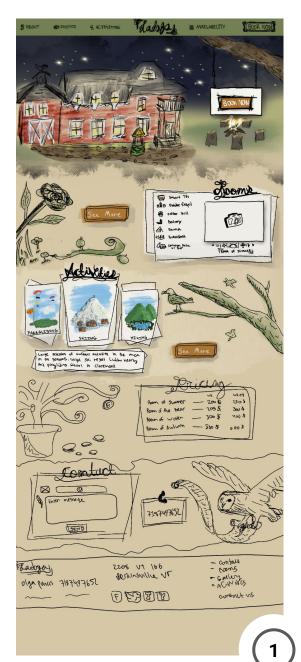
As part of this solo project developed a full-stack web & desktop application using **Tauri**:

- Wrote an extensive API backend in Rust allowing the creation, modification, deletion, and resolution of goals
- Designed an in-house zoomable timeline view in the frontend using ReactJS
- Deployed a PostreSQL database using AWS RDS connecting it to the backend in Rust

This document is my current goal-setting solution. It involves manually performing many automatable-tasks such as executing callbacks, recursively checking goal dependencies, and more.

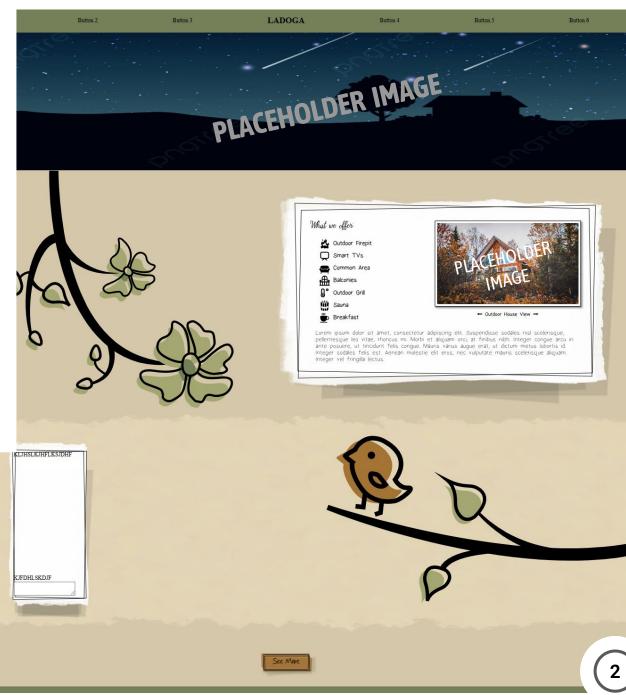
After years of adding to this doc, it now serves as "pseudocode" for the app





This is a two-person **ongoing client project** for a **bed & breakfast business** in New England, USA. The project's first priority is a customer-facing visually-appealing frontend to view information about the B&B, book rooms, see local activities, or contact the owners.

An additional **React-based admin dashboard** will allow management of bookings, cancellations, payments, and customer correspondences. To move off of AirBnB, the platform also includes **Stripe** payments



### **Captions**

- Design mockup made in Procreate
- Custom component showcase

# Technologies

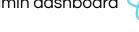
- **Java Spring Boot** backend
- **Gradle** with customized **Kotlin** script to compile the multi-project build
  - HTML / Typescript / SASS for customer-facing website



Contribution

Configured the **Gradle** 

**ReactJS** for admin dashboard

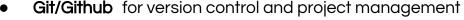


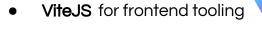
Stripe for payment processing



AWS EC2, RDS, Route53 for hosting









**Procreate** and **Photoshop** for mockups and frontend design





script to build multiple React and non-React frontend projects with a **Spring Boot** backend stack, as well as to execute unit tests and automatically pull production changes on the server

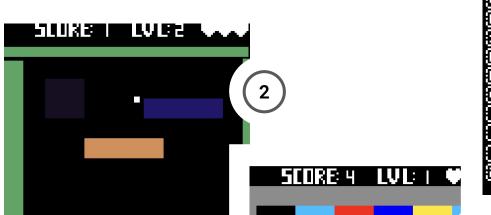
Designed the website frontend mockup and working towards implementing it in HTML/SASS/TS and React components. Additionally working on the backend for the customer facing website, admin dashboard, and Stripe integration.

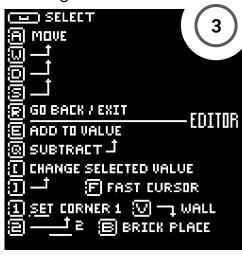
Managing project tasks using Agile with a partner, delegating SVG work and 30% of the frontend



**Solo** project for a **Computer Organization Course** written entirely in **MIPS Assembly**. This submission goes **beyond course expectations** implementing an entire custom implementing an e

editor, a menu, saving to disk, and detailed bitmaps designed with the help of a supplementary **Python** script





# Technologies

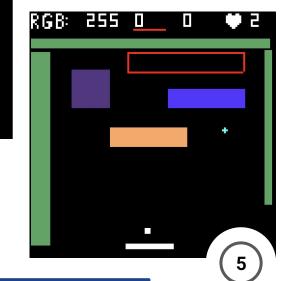
- MIPS Assembly
- Python / Pygame
- Bitmaps













# 6. Main Menu

- 7. Level Selection Screen
- 8. Function to draw an arbitrary multi-digit base 10 number on screen (e.g for score or lives display)

AlekseyPanas/assembly-breakout

- 9. Function to convert two points to a rectangle
- 10. Struct planning for game objects



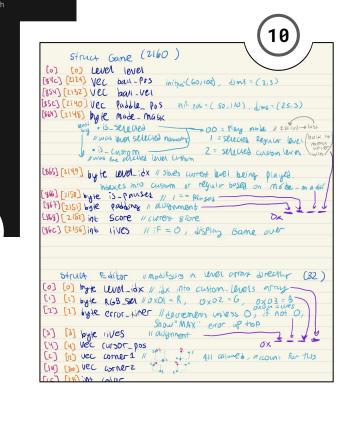
### **Captions**

- Win Screen
- 2. Gameplay

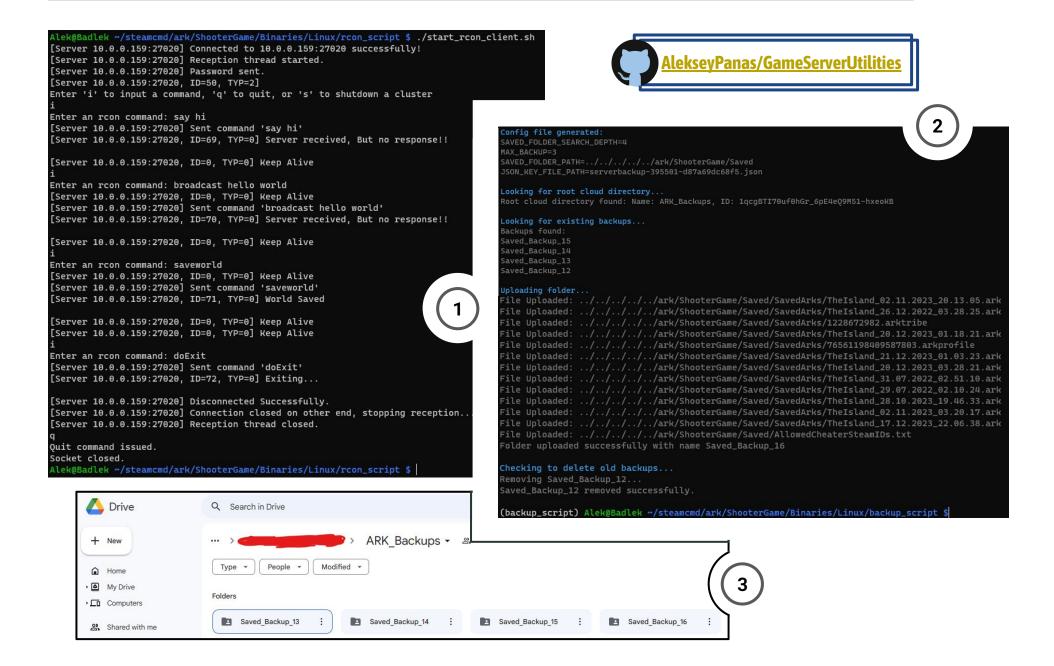
0

- 3. Help Screen
- 4. Game Over Screen
- 5. Level Editor





# Game Server Utilities (ARK)



### **Purpose**

Two scripts were developed to streamline the management of an ARK: Survival Evolved server on a local machine:

- **RCON Script:** Using Python with TCP sockets, this script implements Valve's RCON protocol from scratch, enabling remote execution of server commands outside of the game
- Google Drive Backup Script: This Python script automatically detects the game save folder within the server directory and subsequently uploads it to a Google Drive folder for backup

The ARK server was configured on a custom **Gentoo Linux** installation where the two scripts are now used on a regular basis

# Captions

- 1. **RCON Script** in action
- 2. Execution of the Google Drive backup script
- 3. Shows latest backup appearing in Drive

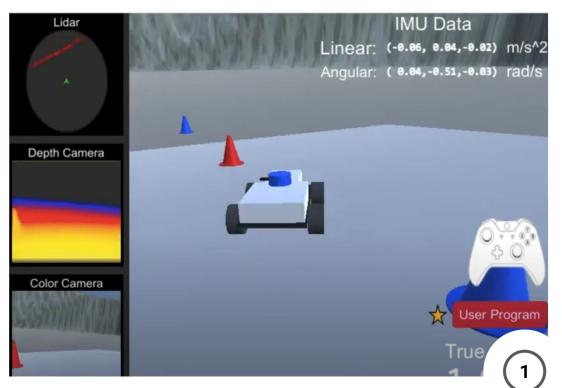
# **Technologies**





- Python
- Gentoo Linux
- TCP Socket Programming
- RCON Protocol
- Google API

# Course



# **Technologies**

- OpenCV
- Numpy
- Depth Camera
- LiDAR
- **SLAM**
- Ubuntu
- **Jetson NANO**
- Sensor Fusion
- Unity
- **Python**
- **AR Codes**

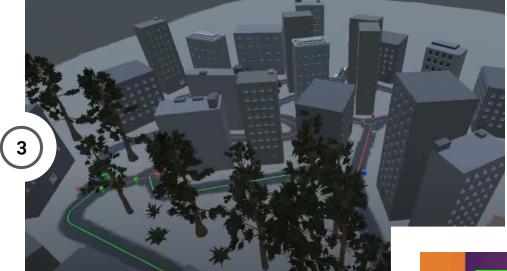






**Final Grand Prix Course Run** 

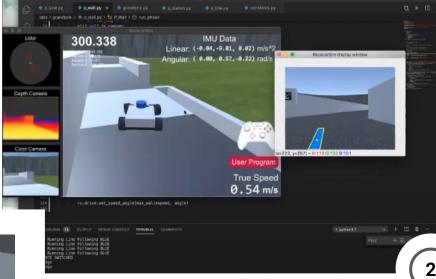
Angular: (-0.01, 0.12,-



### **Purpose**

Completed a month-long course at MIT Beaverworks progressing from the foundations of OpenCV to writing autonomous code for a car to navigate an obstacle course consisting of lane following, cone slaloms, ledge avoidance, and more





# Captions

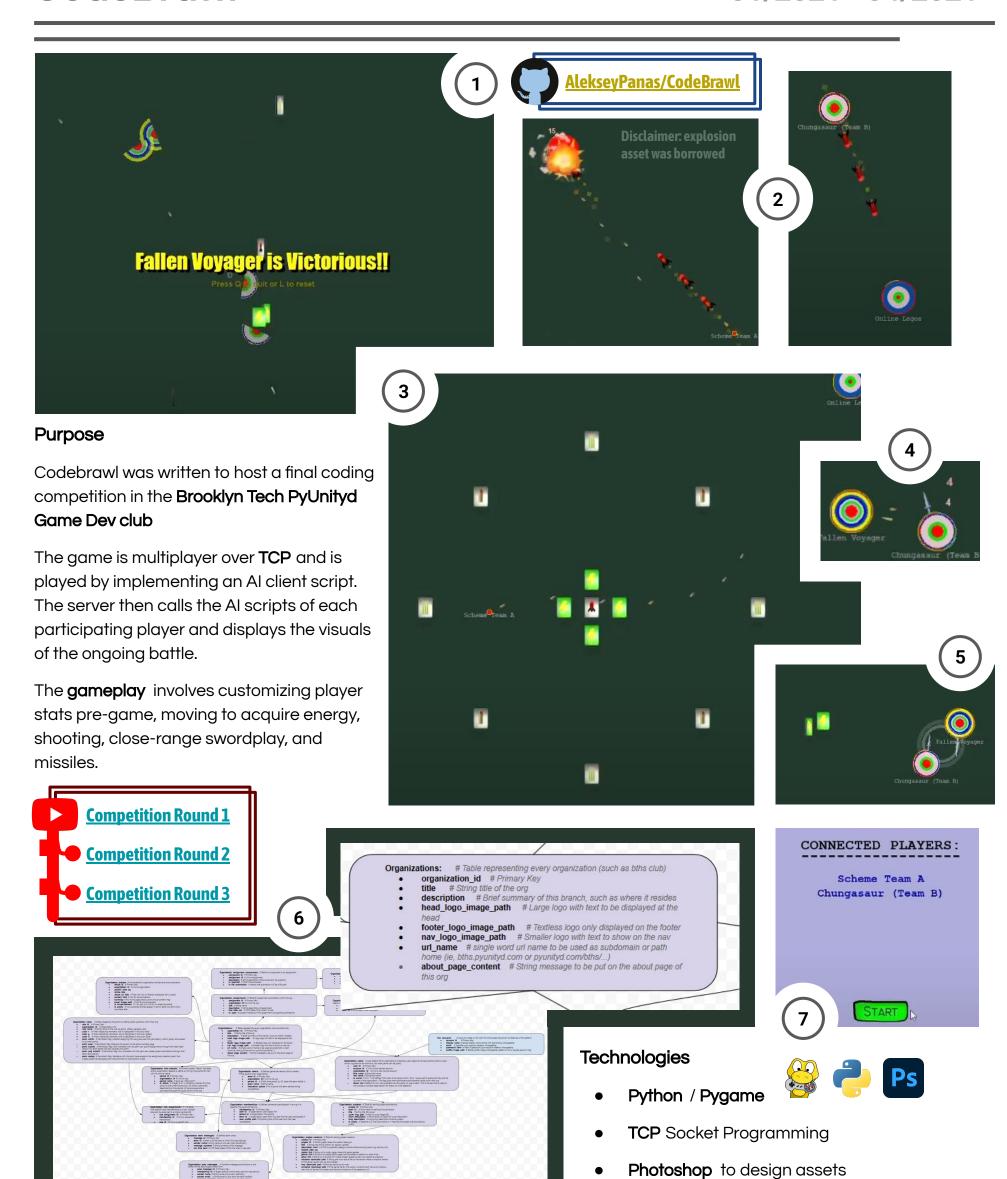
- Cone Slalom
- Ledge avoidance and wall following
- City designed in Unity for navigation testing 3.
- Depth camera closest AR tag detection
- Line follower and AR tag detection

### Course Assignments Involved...

- Wrote a line and lane follower with color switching based on AR tags
- Wrote a cone slaloming algorithm
- Wrote SLAM code to navigate a wall obstacle course and keep track of location
- Incorporated data from a color camera, depth camera, LiDAR, accelerometer, and gyro in the autonomous navigation code applying sensor fusion techniques
- Deployed code to real robotic race car via Ubuntu on Jetson NANO
- Created the video for and contributed to our group's final presentation
- Wrote code for an autonomous time trial course winning 1st place among all students







### **Captions**

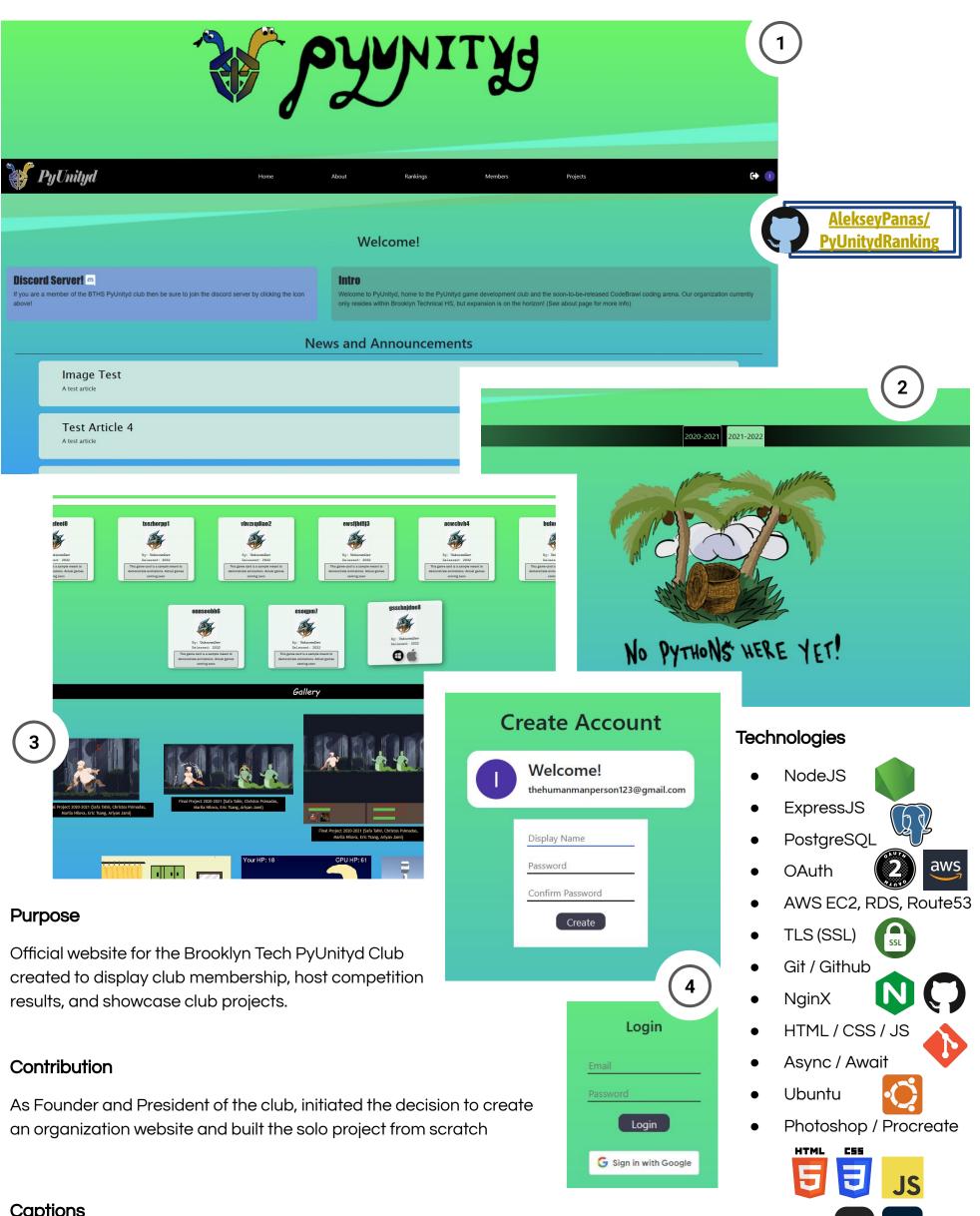
- 1. Victory screen with custom splitting and fading animations on defeat
- 2. Missiles being fired
- 3. Starting arena appearance and bullet firing
- 4. Damage number indicators, sword, and bullets
- 5. Sword blocking mechanic
- 6. Database map for ongoing work to port project to web
- 7. Lobby screen

### Contribution

Developed the entire game start to finish in Python. Brought on two others to assist in writing additional clients in Scala, C#, and Java

### What's Ahead

Ongoing work to port this game to a webapp



# Captions

- 1. Home page
- 2. Art created in **Procreate**
- 3. Project Page with gallery of club members' creations
- Account creation system with google login option

### What's Ahead

After graduating High School, plans were put in action to turn this into a public game development competition platform. That is still an **ongoing** development



Brooklyn Technical High School's Robotics Team (334 TechKnights) participates in an annual FIRST Robotics competition.

Each year, a new game is revealed comprising both autonomous and human-operated phases.

Within a six-week build season, the team designs, constructs, and programs a robot from the ground up to meet the game's challenges.

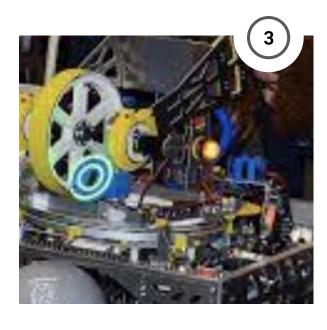
### Captions

- Fun side project: a ride-able "seat bot" coded in C++ and powered by Arduino
- Team334's robot for the 2019 competition
- 2015 Robot used frequently for testing code (LED ring for aiding in computer vision tasks)

### Contribution

Contributed code for four years, writing computer vision in OpenCV with Python and the remaining autonomous and teleop code in Java.

In latter two years, acted as programmer lead implementing an Agile workflow.



# **Technologies**

- OpenCV
  - Numpy
- Java
- PID Loops
  - Jetson NANO **NVIDIA**
- Arduino







Robotic hardware & Sensors

Ubuntu

- - LiDAR, Gyro, Ultrasonic, Camera, Accelerometer, Potentiometer, Pneumatic systems, Motors
- Python

**ROS** 



Git/Github

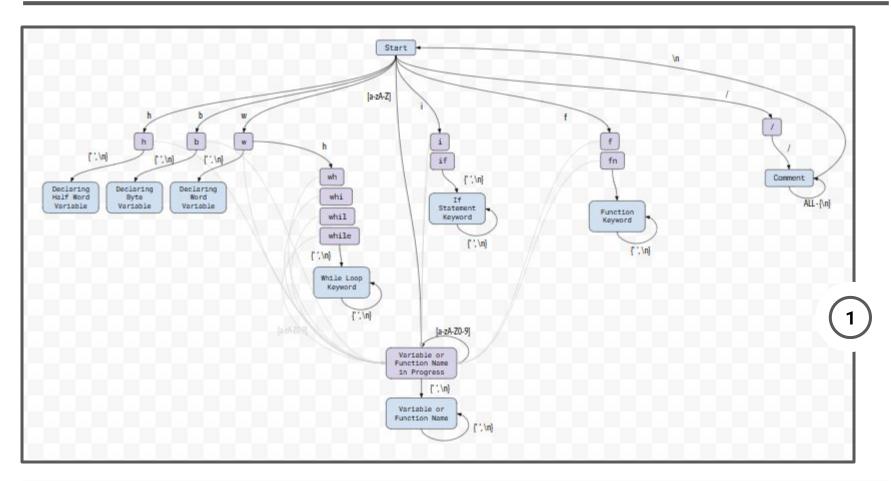


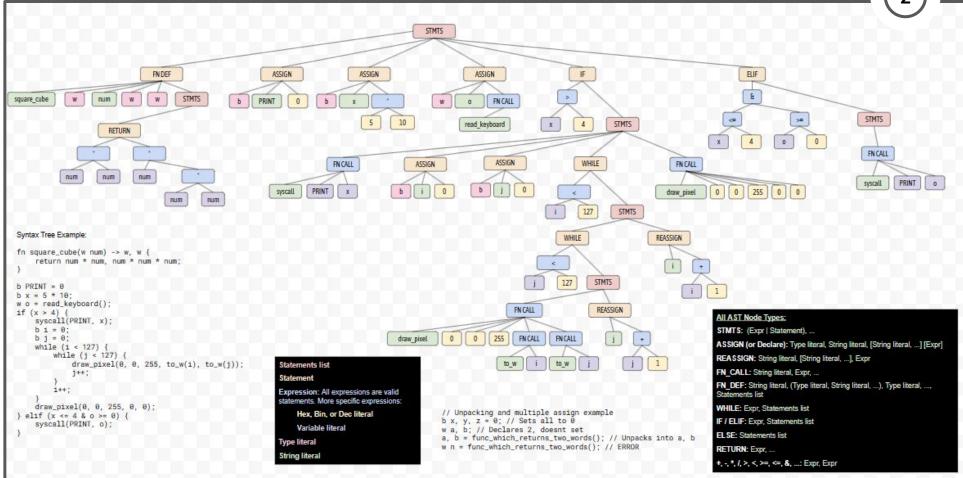


Agile (Shortcut)









A personal solo project conceived after finishing Computer Organization course out of curiosity to write own person language. The project is **ongoing** in its early stages with a completed grammar parser and 10% completed compiler. The language is low level including only byte, word, and halfword datatypes, array functionality, loops, and if statements.



# Captions

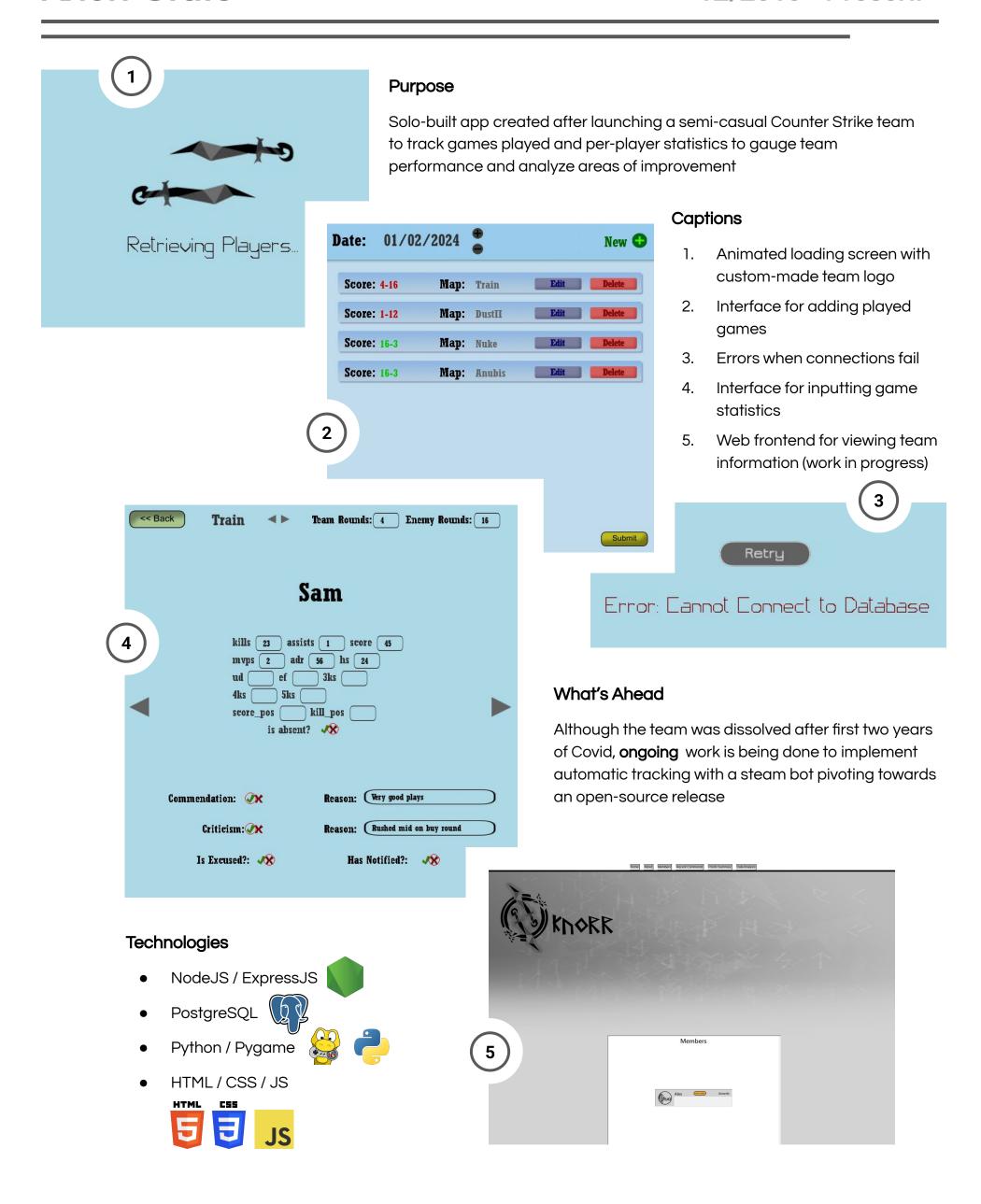
- 1. DFSA diagram initially used when brainstorming how to parse grammar
- 2. Syntax tree when brainstorming language syntax and components

### **Technologies**

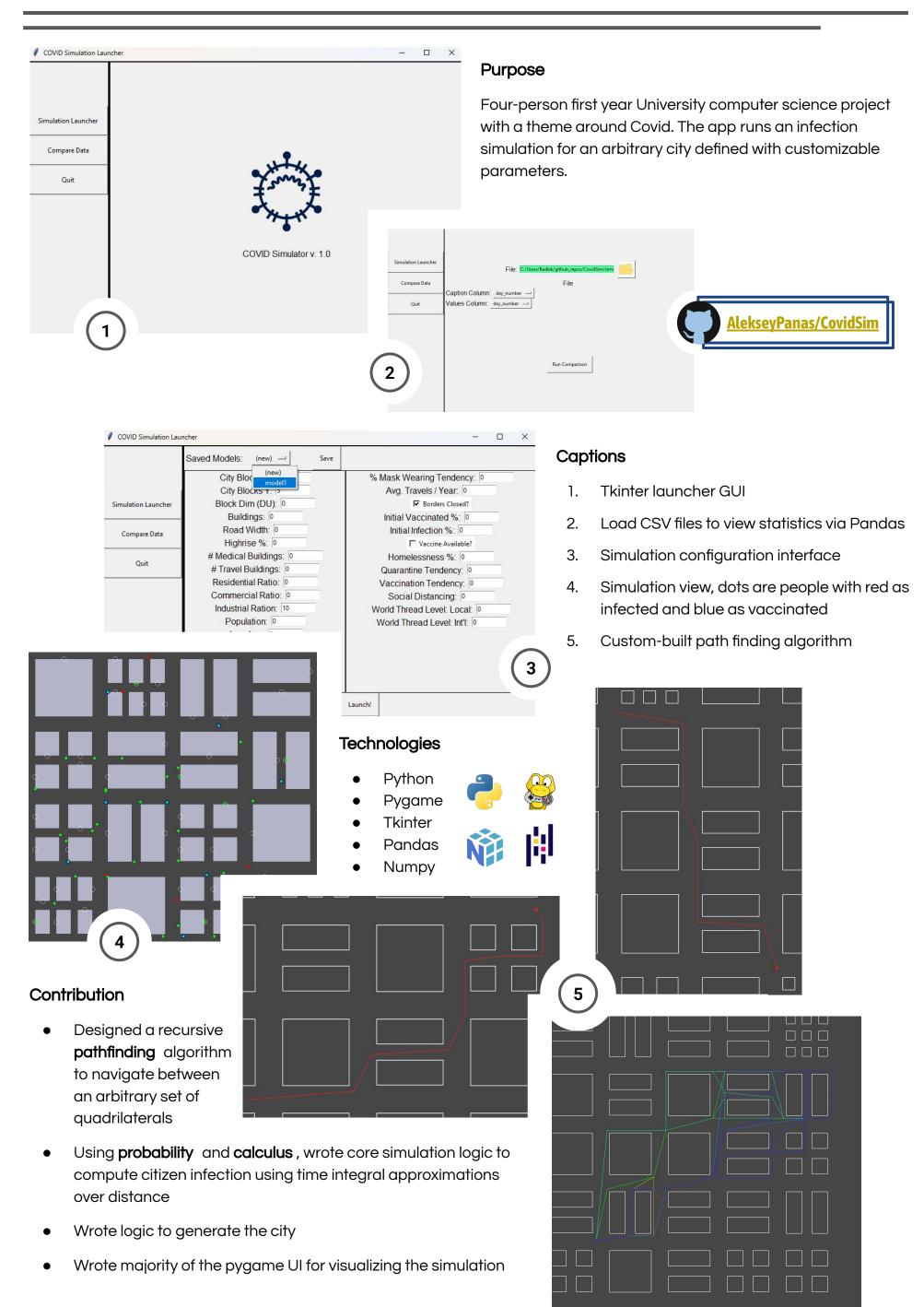
- C
- Abstract Syntax Trees
- MIPS Assembly







CovSim 2021





A fridge management app developed for a hackathon project (UofT Hacks) with one partner. The app is a proof of concept for an embedded software that would run on a smart fridge allowing you to scan products as you put them in to track expiration dates and suggest recipes

**Enter the Expiration Date for GOPI INDIAN STYLE YOGUR** 



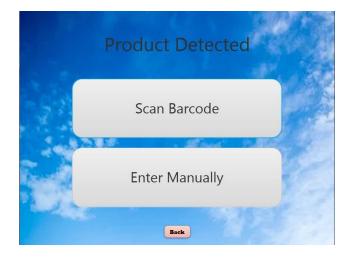
SOUR CREAM

APPLE SAUCE COTTAGE CHEESE

GOPI INDIAN STYLE YOGURT

Captions

- Main screen displaying products
- Manual expiration entry if not deducible from vision code
- 3. Barcode product detection



# **Technologies**

Back

- Java / JavaFX
- Google Zxing
- OpenCV

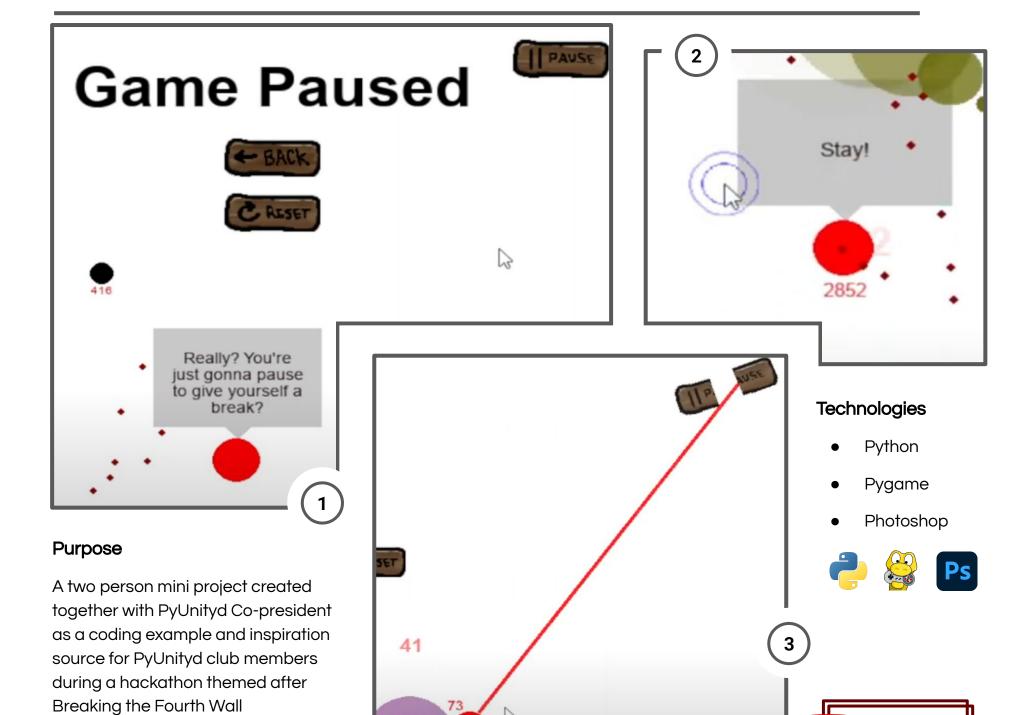


# Contribution

Wrote approximately 60% of the UI, and worked collectively with partner to solve the computer vision component of detecting barcodes and reading expiration dates

**Detected Product: GOPI INDIAN STYLE YOGURT** 





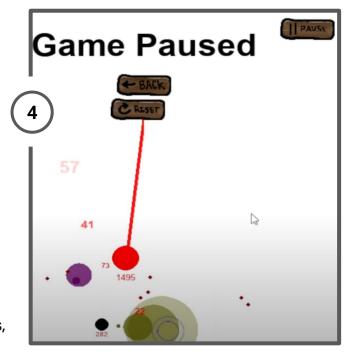
The game involves an arcade-style boss fight where the boss uses the pause and reset menu buttons to their advantage. The boss also occasionally traps your mouse pointer in a specific location

# Contribution

Wrote the entire game with the exception of the boss' shooting Al. Also designed and created button assets in Photoshop

# Challenges

Using Pygame meant that the speech boxes, pause menu, and other key features had to be implemented from scratch.



# AlekseyPanas/BreakingFourthWall

# Captions

 Boss aware of game being paused

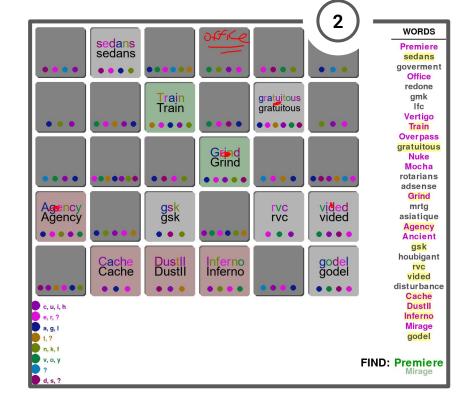
**Game Demo** 

- Boss traps mouse cursor
- Boss destroys pause button
- 4. Boss knocks reset button out of pause menu so that the player has to avoid it



# **Captions**

- [2020] Converts JSON death logs from Minecraft Hardcore playthroughs hosted with friends into a visualization (using OpenCV for image filters and Pygame for drawing and exporting)
- [2022] Puzzle game initially created to make map choosing more fun when playing Counter Strike with friends. Purple words from the word list cycle at the bottom right with each revealed tile and will turn green if revealed while prompted. Colored dots help indicate letters and their order for hidden word tiles.
- [2019] A small top-view turn-based combat game where you control units and upgrade bases
- [2020] 2D inverse kinematics where the arms deform to reach specified locations.



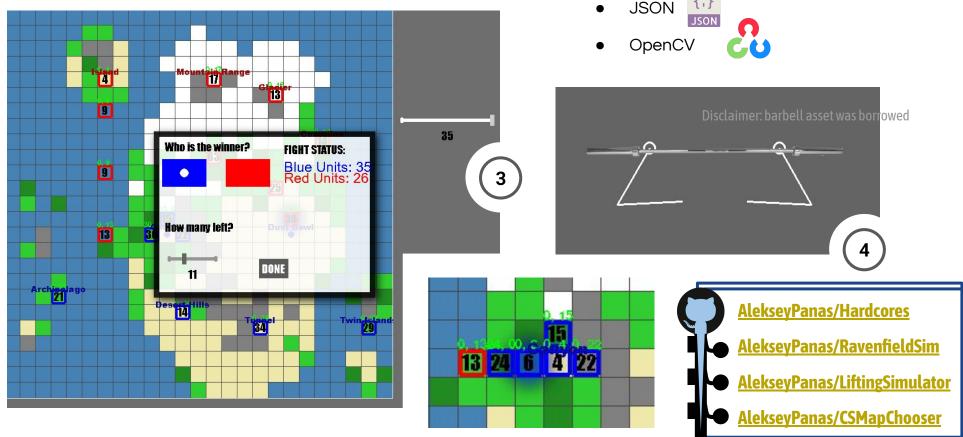
# **Technologies**

Python / Pygame





JSON



Task Race 2020



### What's Ahead

While I have already extensively used this app personally, there are plans to expand it to polish it as a finished product:

- Port to a web app
- Add a more sophisticated settings menu for configuring tasks and opponents
- Add matchmaking to go up against real opponents who have a task list of similar estimated length
- Add auto time estimation for common tasks

Polar Defense 2019

### **Purpose**

Submission for an open-ended extra credit assignment for a calculus class in high school with a task to develop an educational piece of media on a subject from the curriculum

Choosing polar coordinates as the topic, this small game was developed, requiring the player to convert cartesian coordinates to polar to fire the turret at various targets.



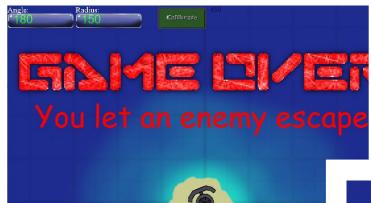
# **Technologies**

- Python
- Pygame
- Photoshop

















### Contribution

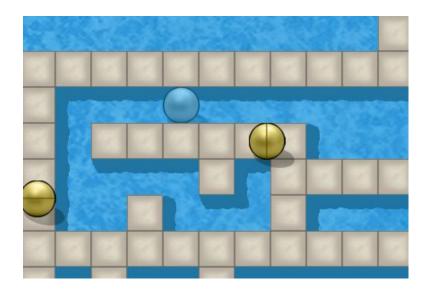
Wrote all the game code while a partner created the boat, turret, and buoy assets.

The remaining assets, including the tutorial screen, were done collectively





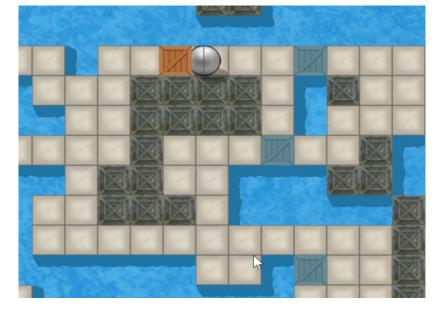




Clone of a Miniclip flash game called "SilverSphere" developed as a birthday present for my mom since she enjoyed that game and could no longer play it once flash got taken down.

This solo project features new levels and a simple level editor over the original game





Disclaimer: Majority of assets were borrowed from google images or the original SilverSphere Miniclip game

# Technologies

- Python
- Pygame
- Photoshop







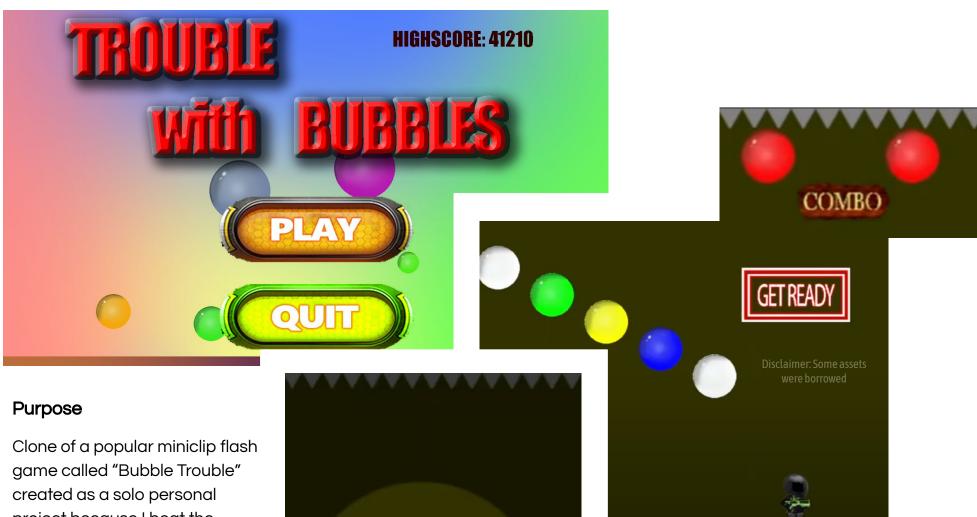




# **Trouble with Bubbles**



AlekseyPanas/ TroubleBubbles



project because I beat the original game and wished to make additional more challenging levels



- Python
- Pygame
- Photoshop





